



SYSTEM AND PROCESS ASSESSMENT RESEARCH LABORATORY

SPAR Lab

Civil, Architectural and Environmental Engineering • 103/104-E Butler-Carlton Hall

SMART ROCK TECHNOLOGY FOR REAL-TIME MONITORING OF BRIDGE SCOUR AND RIPRAP EFFECTIVENESS – GUIDELINES AND VISUALIZATION TOOLS

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OUTLINE OF THIS PRESENTATION

- **The Smart Rock Monitoring Concept**
- **Design and Prototyping**
- **Localization and Effectiveness**
- **Field Test Demonstration**
- **Concluding Remarks**



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MISSOURI
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THE SMART ROCK MONITORING CONCEPT

- **Two Application Scenarios**

- **Scour Depth**

- ✓ *Deposits at a bridge pier or abutment are washed away to form a scour hole with unknown location and depth.*

- **Countermeasure Effectiveness**

- ✓ *Move of rocks leads to the loss of a rip-rap countermeasure for bridge scour protection.*

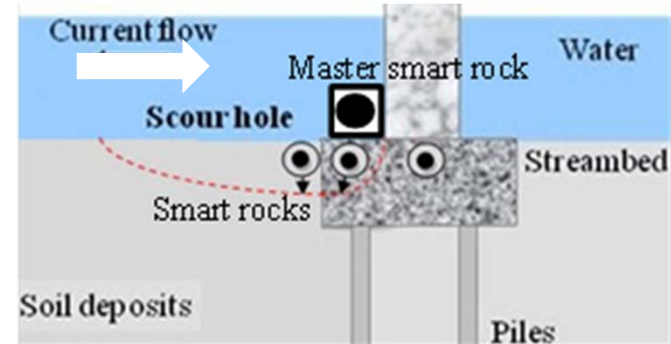


Fig. 1 Maximum Scour Depth Monitoring

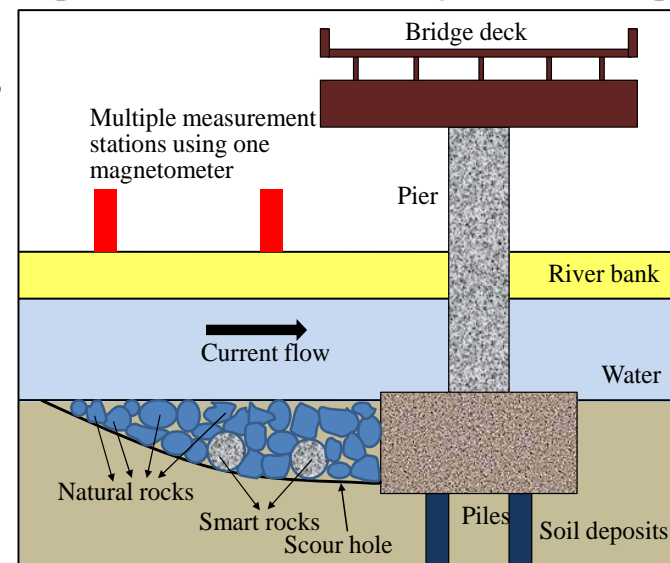


Fig. 2 Scour Countermeasure Monitoring



DESIGN AND PROTOTYPING

- **Arbitrarily Oriented System (AOS)**
 - ✓ *Monitored along the river bank or on the bridge deck*
 - ✓ *Most complicated in smart rock localization*



AOS Model of Smart Rocks



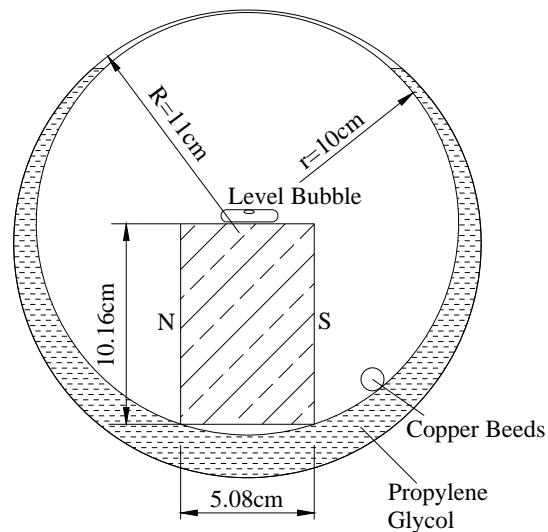
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DESIGN AND PROTOTYPING

- **Automatically Pointing-South System (APSS)**

- ✓ *Monitored along the river bank*
- ✓ *Measurement station located in South or North pole of the magnet*
- ✓ *Rapid convergence and high accuracy of APSS location*
- ✓ *However, easily affected by ferromagnetic substances*



(a) Schematic View



(b) Prototype Smart Rock

APSS Model of Smart Rocks



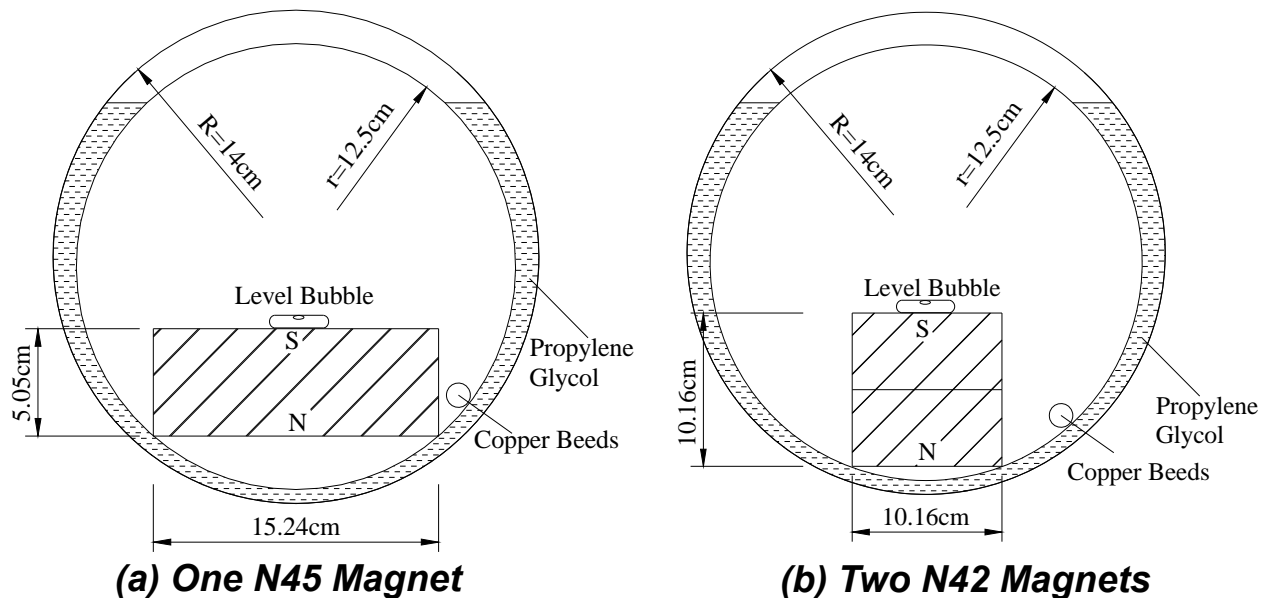
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DESIGN AND PROTOTYPING

- **Automatically Pointing-Up System (APUS)**

- ✓ *Automatically Pointing to Upward System (APUS)*
- ✓ *Measurement apparatus set on the bridge deck*
- ✓ *Gravity-orientated direction, reduces the degree of freedom, less effect by ferromagnetic substance*



(b) Prototype Smart Rock

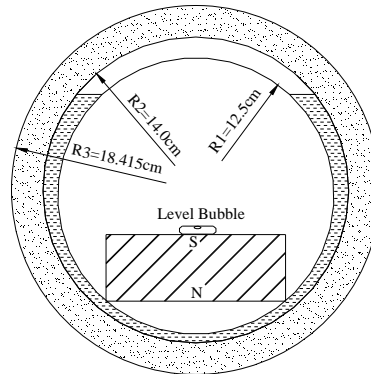


DESIGN AND PROTOTYPING

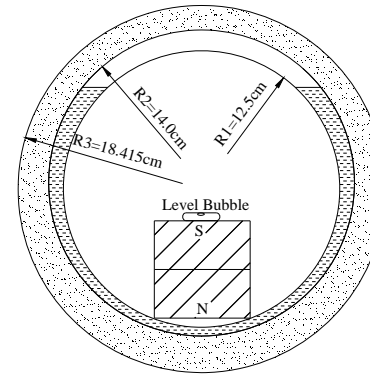
- **Concrete Encasement and Fabrication**

- 36.83-cm-diameter mold with a concrete density of 1495 kg/m³
- Fabrication process

One N45 Magnet



Two Stacked N42 Magnet



1. Mix fiber concrete



2. Place APUS inside a mold



3. Fill the mold with concrete



4. Cure the concrete in water for 14 days



LOCALIZATION AND EFFECTIVENESS

- **Ambient Magnetic Field at Q Station in Absolute XYZ Coordinate System**

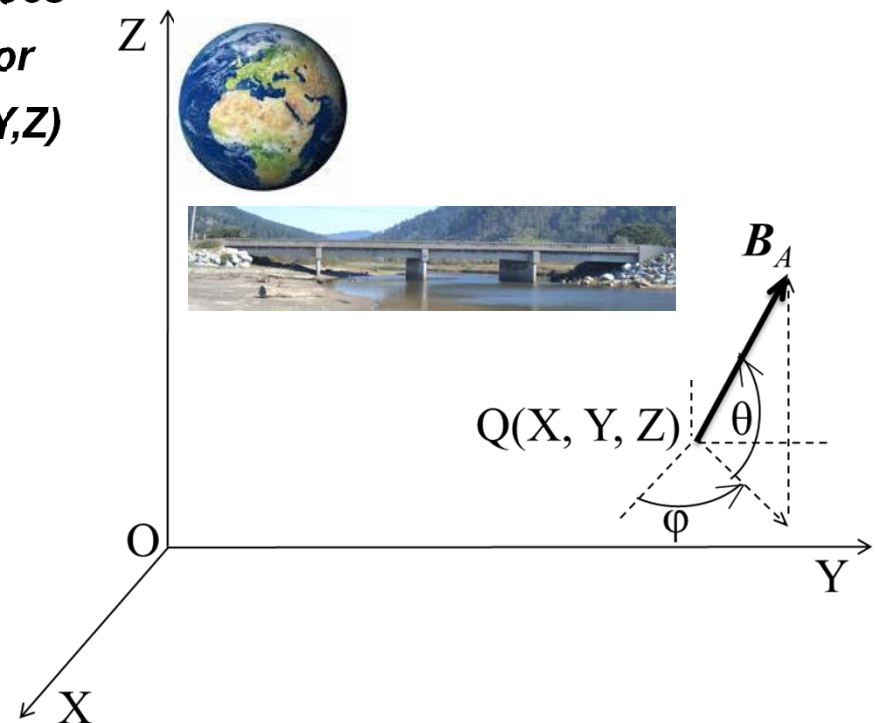
- ✓ *Ambient Ferromagnetic Substances*
- ✓ B_A , *Ambient Magnetic Field Vector at a Measurement station, Q (X,Y,Z)*
- ✓ *Three components of B_A :*

$$B_{XA} = B_A \cos \theta \cos \varphi$$

$$B_{YA} = B_A \cos \theta \sin \varphi$$

$$B_{ZA} = B_A \sin \theta$$

- ✓ B_A , *measured by magnetometer*
- ✓ θ ($0, \pi$) and φ ($0, 2\pi$) *measured by an orientation device*



LOCALIZATION AND EFFECTIVENESS

- **Total Magnetic Field at Q Station in Absolute XYZ Coordinate System**

✓ **Total Magnetic field intensity:**

$$B = \sqrt{(B_{XM} + B_{XA})^2 + (B_{YM} + B_{YA})^2 + (B_{ZM} + B_{ZA})^2} \quad Z$$

✓ **$B = B(B_A, \theta, \phi, k, X_M, Y_M, Z_M, \alpha, \beta, \gamma, X, Y, Z)$ at a Measurement station, Q (X,Y,Z)**

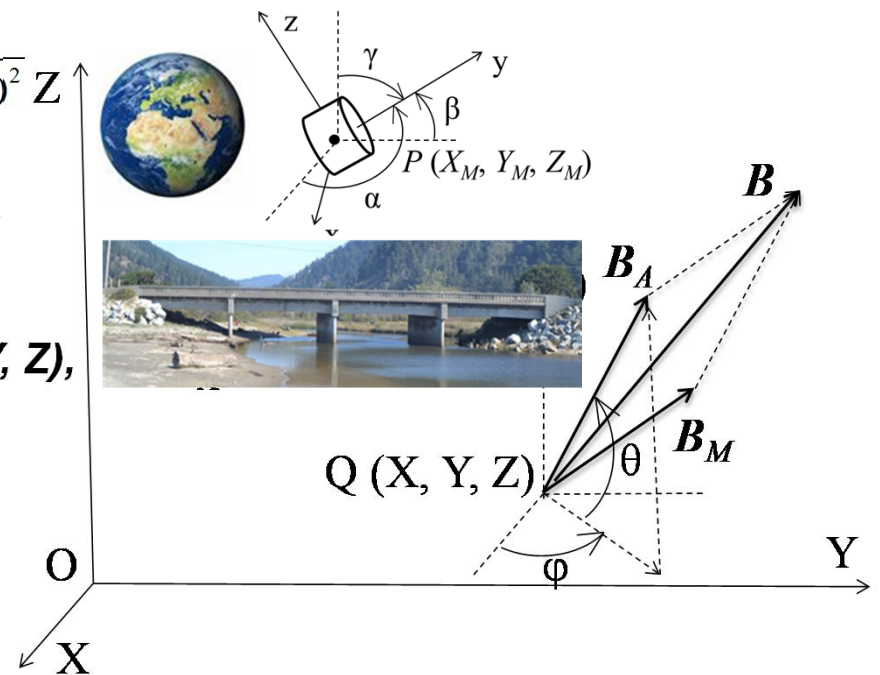
✓ **Given k, θ, ϕ and B_A at each (X, Y, Z),**

$$B = B(X_M, Y_M, Z_M, \alpha, \beta, \gamma)$$

✓ **Magnet's effect:**

$$\begin{pmatrix} B_{XM} \\ B_{YM} \\ B_{ZM} \end{pmatrix} = \mathbf{T}^{-1} \begin{pmatrix} k3xy / r^5 \\ k(2y^2 - x^2 - z^2) / r^5 \\ k3zy / r^5 \end{pmatrix}$$

$$\mathbf{T} = \begin{bmatrix} \cos \beta \cos \gamma & \cos \beta \sin \gamma & -\sin \beta \\ \sin \alpha \sin \beta \cos \gamma - \cos \alpha \sin \gamma & \sin \alpha \sin \beta \sin \gamma + \cos \alpha \cos \gamma & \sin \alpha \cos \beta \\ \cos \alpha \sin \beta \cos \gamma + \sin \alpha \sin \gamma & \cos \alpha \sin \beta \sin \gamma - \sin \alpha \cos \gamma & \cos \alpha \cos \beta \end{bmatrix}$$



LOCALIZATION AND EFFECTIVENESS

- **Localization Algorithm**

- **Unknown Orientation**

✓ *SRSS error between predicted intensity $B_i^{(P)}$ and the measured intensity $B_i^{(M)}$,*

$$J(X_M, Y_M, Z_M, \alpha, \beta, \gamma) = \sqrt{\sum_{i=1}^n [B_i^{(P)} - B_i^{(M)}]^2}$$

$$\frac{\partial J(X_M, Y_M, Z_M, \alpha, \beta, \gamma)}{\partial X_M} = 0$$

$$\frac{\partial J(X_M, Y_M, Z_M, \alpha, \beta, \gamma)}{\partial Y_M} = 0$$

$$\frac{\partial J(X_M, Y_M, Z_M, \alpha, \beta, \gamma)}{\partial Z_M} = 0$$

$$\frac{\partial J(X_M, Y_M, Z_M, \alpha, \beta, \gamma)}{\partial \alpha} = 0$$

$$\frac{\partial J(X_M, Y_M, Z_M, \alpha, \beta, \gamma)}{\partial \beta} = 0$$

$$\frac{\partial J(X_M, Y_M, Z_M, \alpha, \beta, \gamma)}{\partial \gamma} = 0$$

- **Known Orientation ($\alpha=0$, $\beta=0$, and $\gamma=0$)**

$$J(X_M, Y_M, Z_M) = \sqrt{\sum_{i=1}^n [B_i^{(P)} - B_i^{(M)}]^2}$$

$$\frac{\partial J(X_M, Y_M, Z_M)}{\partial Y_M} = 0$$

$$\frac{\partial J(X_M, Y_M, Z_M)}{\partial Z_M} = 0$$

$$\frac{\partial J(X_M, Y_M, Z_M)}{\partial X_M} = 0$$



LOCALIZATION AND EFFECTIVENESS

- **Experimental Validation Procedure**
 - Before a smart rock is deployed, the ambient magnetic field of the Earth and environmental effects was evaluated at each measurement point either by a scalar magnetometer and an orientation device or by a three-component magnetometer.
 - After the smart rock is deployed, the total magnetic field of the magnet and the ambient field was measured with the same magnetometer at various points around the smart rock.
 - The coordinates of measurement points were surveyed by a total station – a survey instrument.
 - The intensity and coordinate measurements at six or more stations allowed the determination of the smart rock's location.

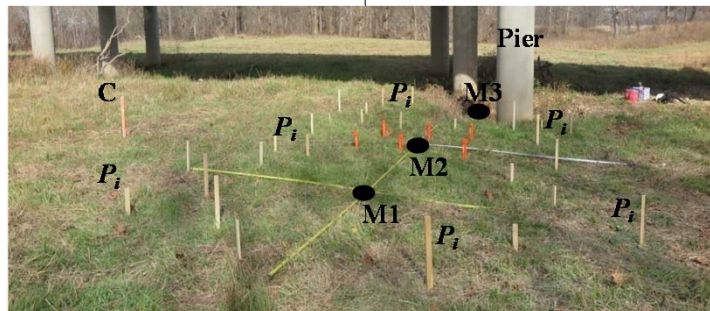
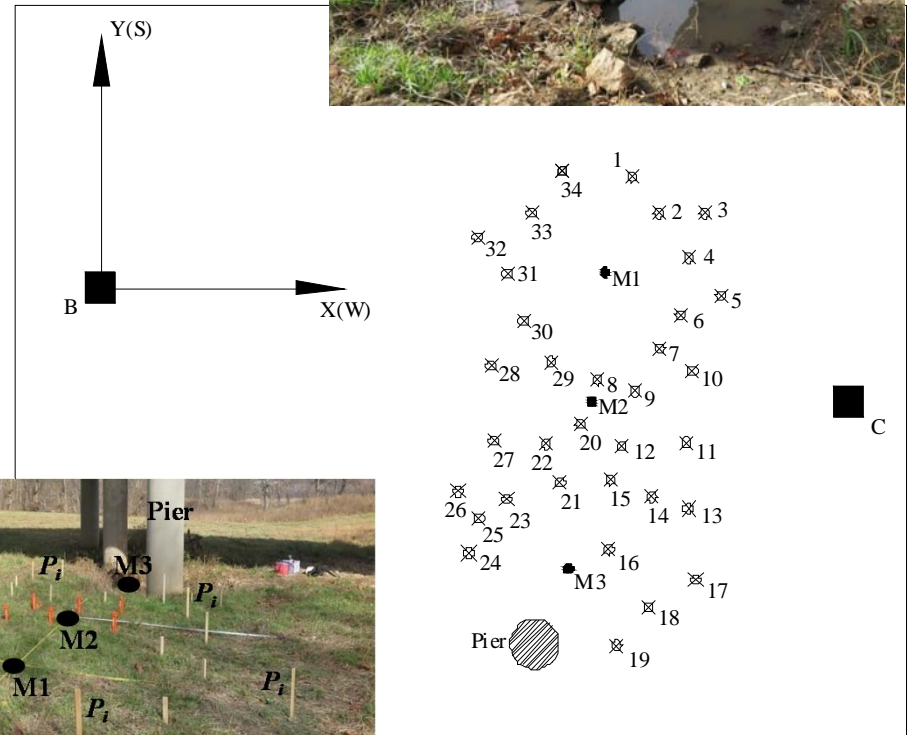


LOCALIZATION AND EFFECTIVENESS

- **Experimental Validation**

- **Test Setup**

- ✓ *A scour experienced pier*
 - ✓ *Three Locations M1, M2, and M3 for AOS and APSS*
 - ✓ *Total 34 measurement points*
 - ✓ *Total Station at Point B to survey coordinates of three smart rocks' locations and 34 sensor positions*
 - ✓ *MFDD was set at the 34 points to measure the angles of θ and φ*



LOCALIZATION AND EFFECTIVENESS

- **Experimental Validation**
 - **Test Results ($M3_{APSS}$)**

Location of Sensor Head	X(m)	Y(m)	Z(m)	$B_i^{(M)}$ (nT)
P9	10.940	-2.065	-0.657	52766
P11	11.991	-3.082	-0.558	52422
P12	10.670	-3.162	-0.670	55203
...
P20	9.822	-2.717	-0.635	55164
P21	9.413	-3.877	-0.748	63734
P23	8.313	-4.215	-0.501	59204
P25	7.750	-4.591	-0.858	58350
P26	7.315	-4.055	-0.726	56087
P27	8.043	-3.046	-0.553	55198
Predicted APSS Location $M3_{APSS}$	9.527	-5.520	-1.850	N/A
Measured APSS Location $M3_{APSS}$	9.576	-5.584	-1.822	
Location Prediction Error for $M3_{APSS}$	-0.049	0.064	-0.028	
SRSS Error in Coordinate	0.085m			



LOCALIZATION AND EFFECTIVENESS

- **Experimental Validation**
 - Test Results ($M3_{AOS}$)

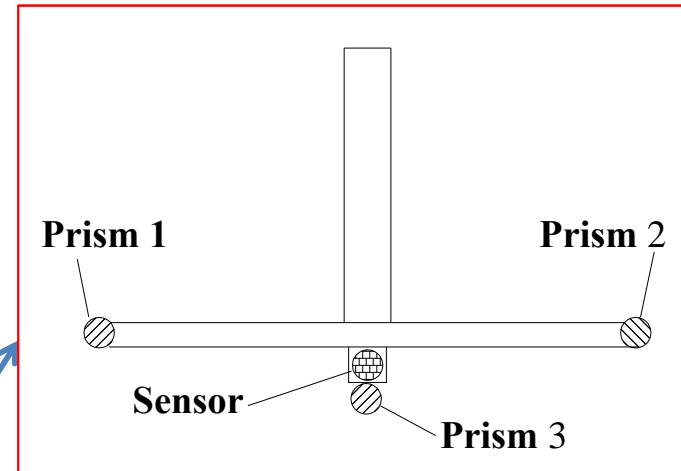
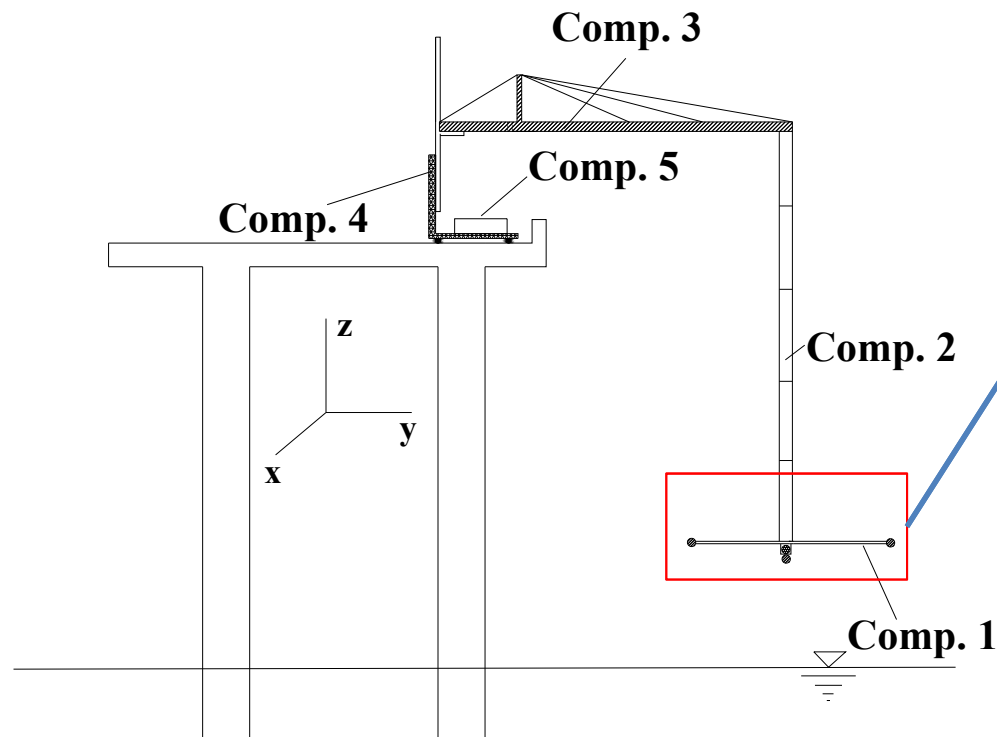
Location of Sensor Head	X(m)	Y(m)	Z(m)	$B_i^{(M)}$ (nT)
P9	10.940	-2.065	-0.667	52651
P12	10.670	-3.162	-0.680	54660
P13	12.031	-4.399	-0.745	52095
...
P20	9.822	-2.717	-0.645	54929
P21	9.413	-3.877	-0.758	62508
P23	8.313	-4.215	-0.511	59364
P25	7.750	-4.591	-0.868	59523
P26	7.315	-4.055	-0.736	56642
P27	8.043	-3.046	-0.563	55399
Predicted AOS Location $M3_{AOS}$	9.514	-5.519	-1.860	N/A
Measured AOS Location $M3_{AOS}$	9.576	-5.584	-1.837	
Location Prediction Error for $M3_{AOS}$	-0.062	0.065	-0.023	
SRSS Error in Coordinate	0.093m			



FIELD TEST DEMONSTRATION

- Test “Crane” Design

- Lightweight, easy installation, rapid assembling, and cost effectiveness
- Minimal wind-induced disturbance
- Non-magnetic materials in proximity to the sensor



FIELD TEST DEMONSTRATION

- Test “Crane” Prototype/Product



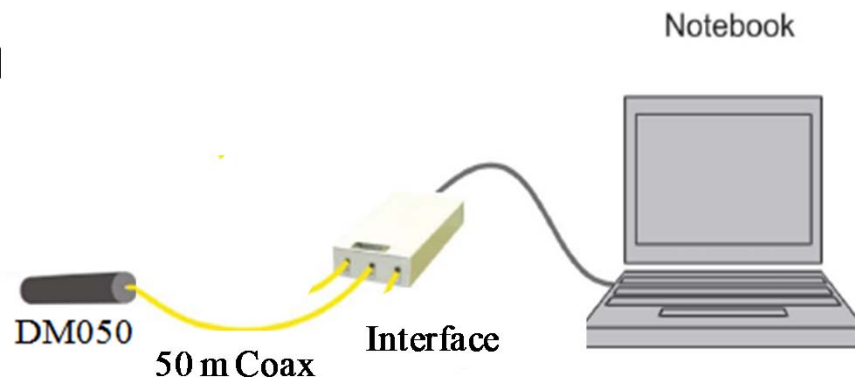
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FIELD TEST DEMONSTRATION

- **Three-axis Flux Digital Magnetometer (STL)**

- Manufactured by Systemtechnik Ludwig GmbH, Konstanz, Germany
- STL DM050: measure X-, Y- and Z- component and total field
- 50 meters Coax cable for power and data transmission
- Interface : Coax Ethernet Hub for connection of up to 3 magnetometers
- STL GradMag software installed in a Notebook for full controlling of measurement, data acquisition and viewer
- Field range: $\pm 1,000,000\text{nT}$
- Resolution: 0.002nT
- Maximum sample rate: 1



FIELD TEST DEMONSTRATION

- HWY1 Waddell Creek Bridge, CA



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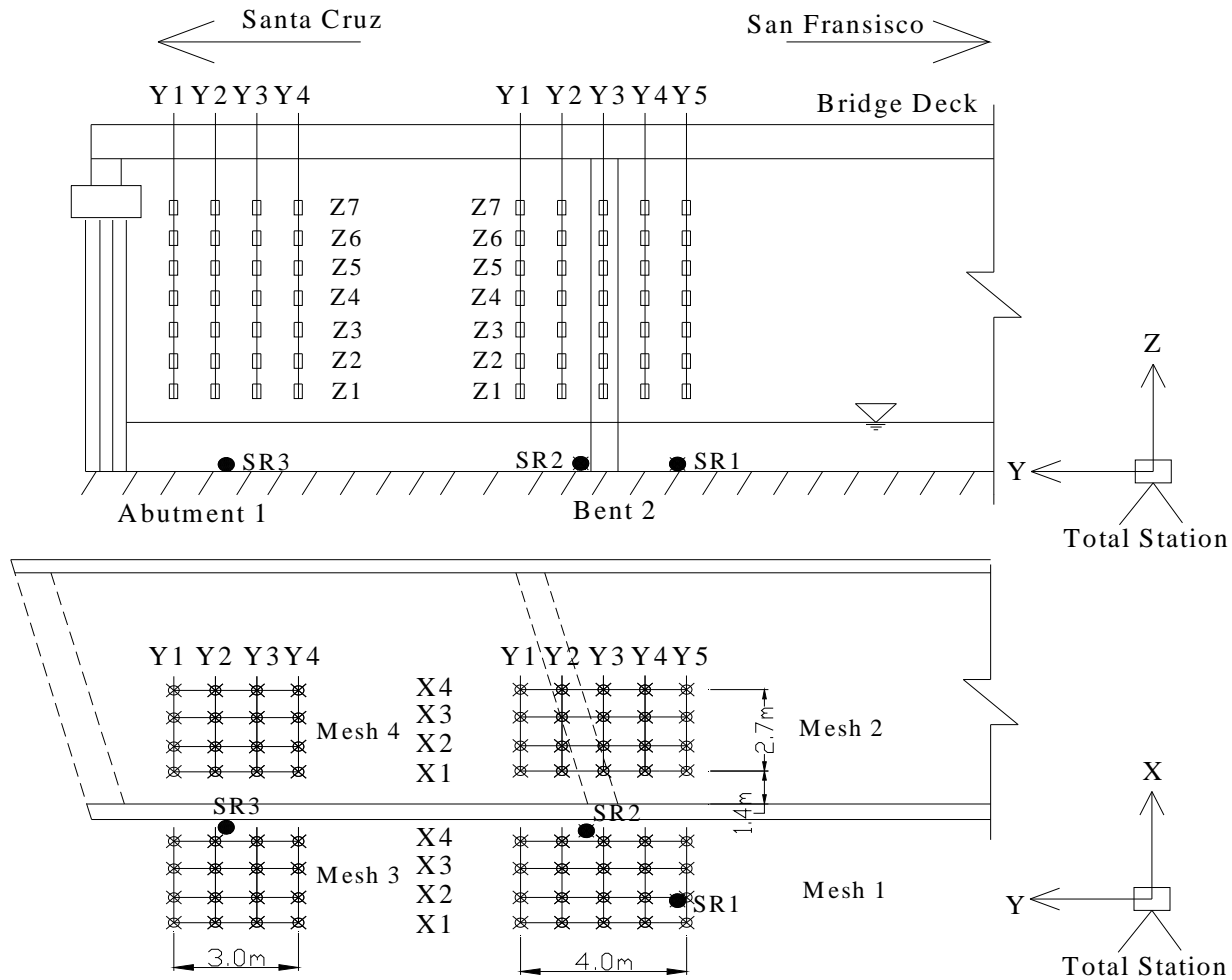
FIELD TEST DEMONSTRATION

- **Setup and Layout on Bridge Deck**
- **Test Procedure**
 - **Set a Cartesian Coordinate System**
 - **Ambient Magnetic Field Measurement**
 - **Deployment of Smart Rocks**
 - **Measurement of the Total Magnetic Field**
- **Results from Bridge Deck Measurements**



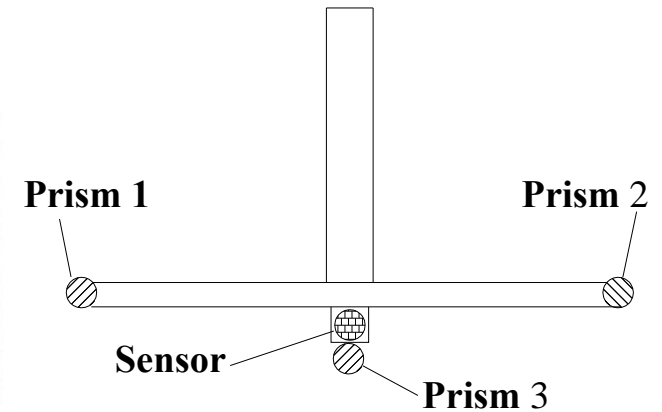
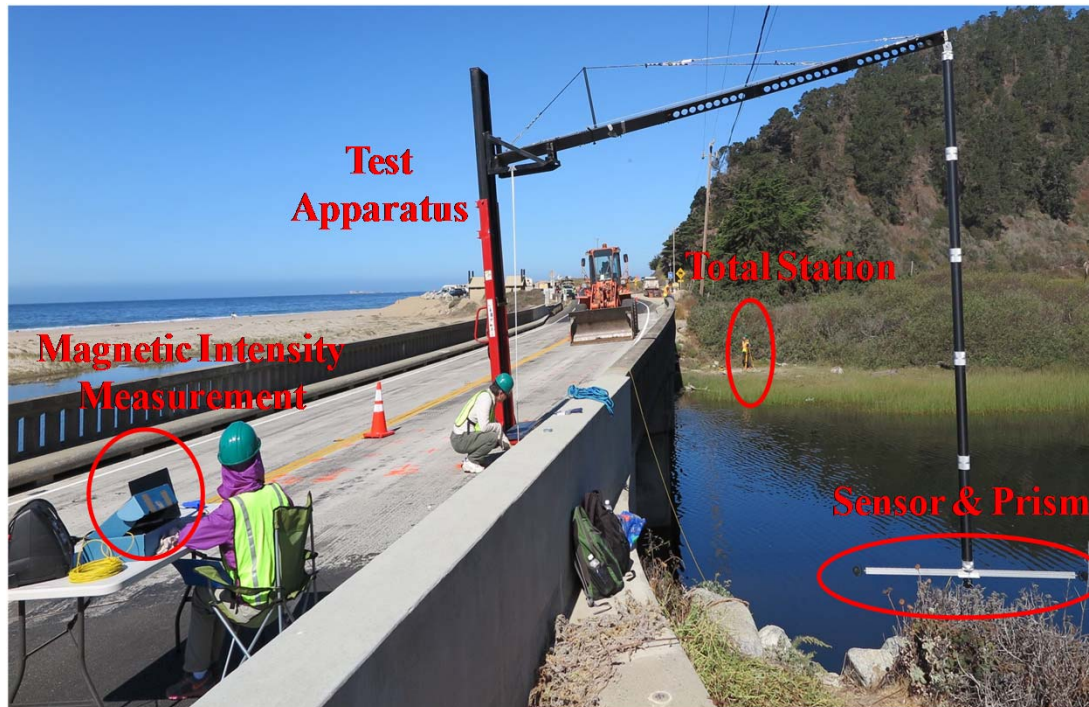
FIELD TEST DEMONSTRATION

- Measurement Station Layout on Bridge Deck



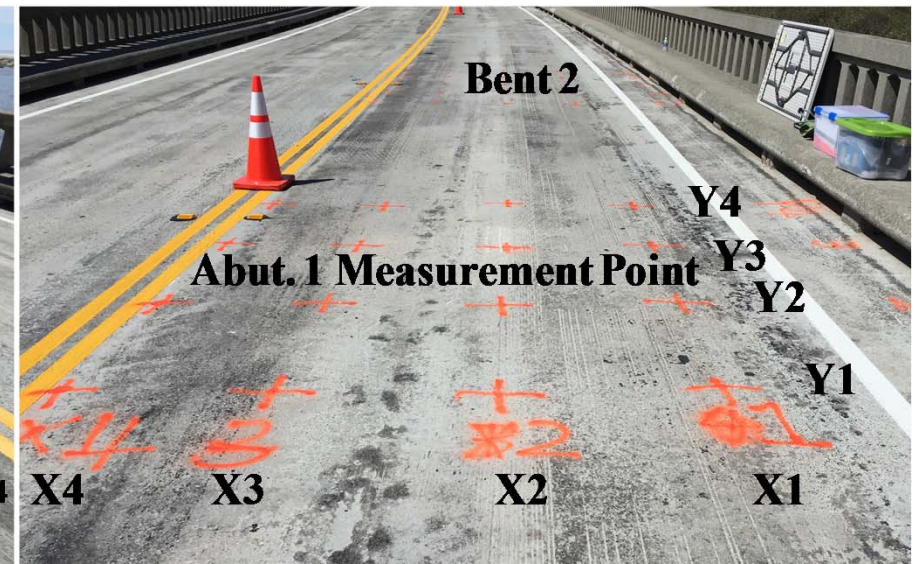
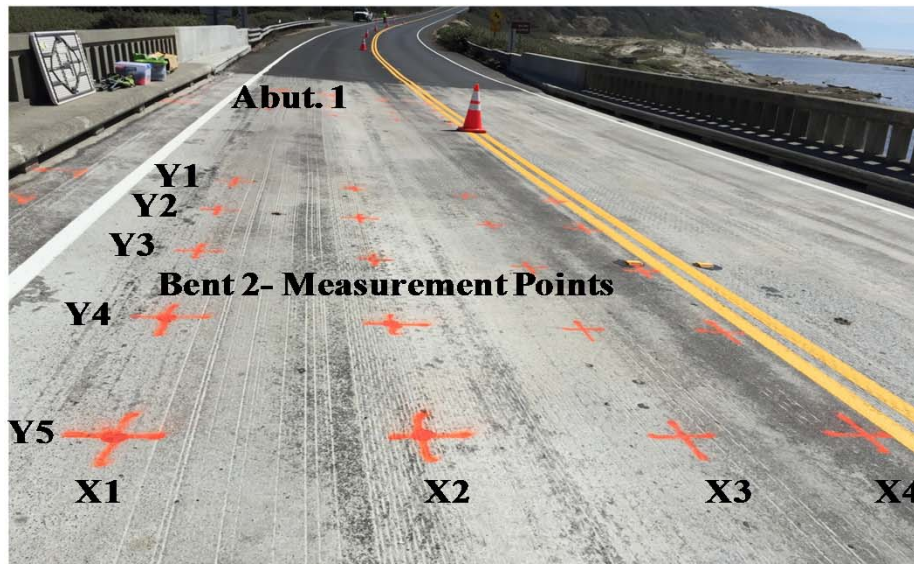
FIELD TEST DEMONSTRATION

- Test Setup and Layout



FIELD TEST DEMONSTRATION

- Test Set up and Layout
 - Measurement Points Layout on the Bridge Deck

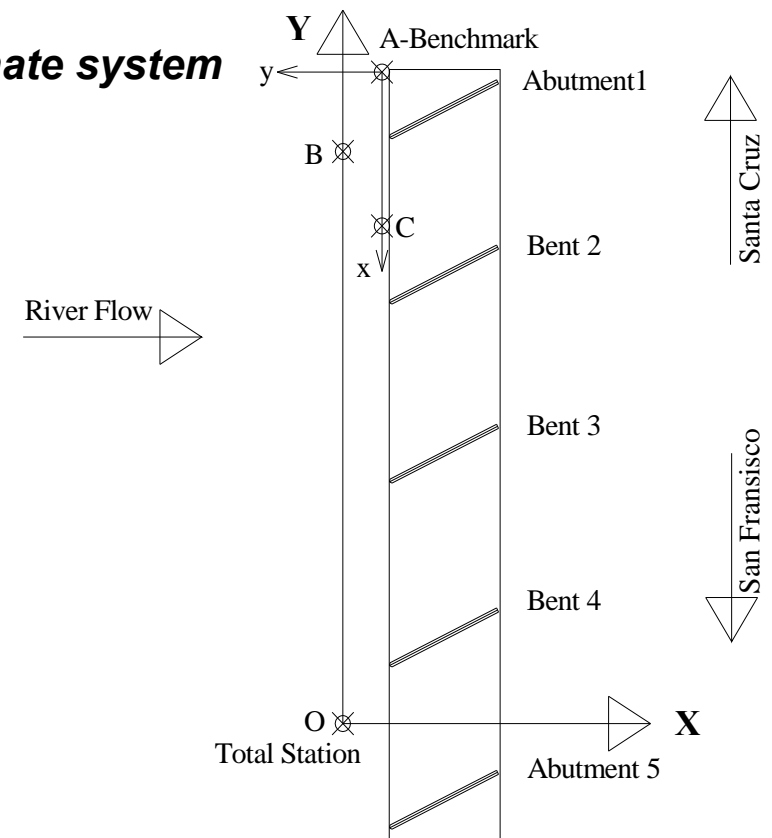


FIELD TEST DEMONSTRATION

- **Test Procedure**

- **Set a Cartesian coordinate system O-XY**

- ✓ *Point A- Permanent Benchmark*
 - ✓ *Total station at Point A to set coordinate system as A-xy*
 - ✓ *Survey Point B and O under A-xy coordinate system*
 - ✓ *Set up total station at Point O to determine the final coordinate O-XY*

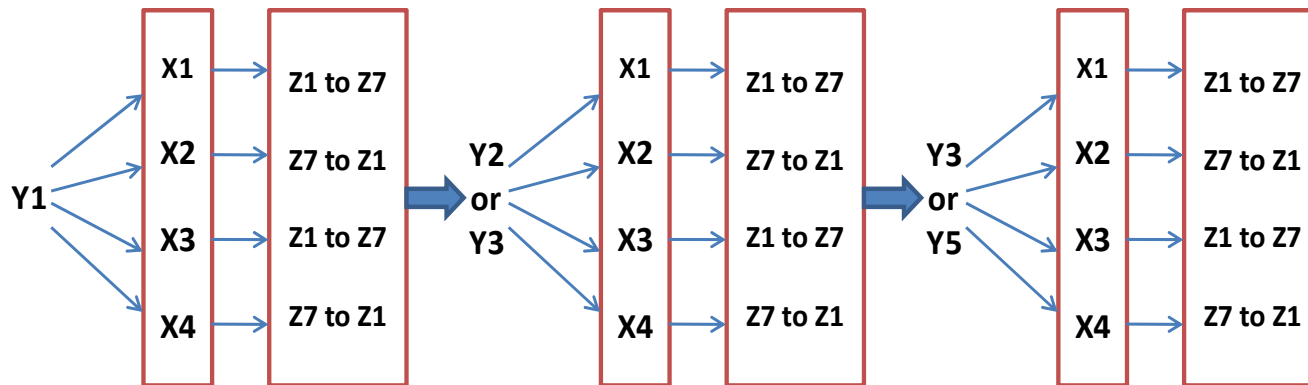


FIELD TEST DEMONSTRATION

- **Test Procedure**

- **Measure the Ambient Magnetic Field**

- ✓ *Magnetic field from Earth and ambient ferromagnetic constructions*
 - ✓ *Conduct before deployment of the smart rock*
 - ✓ *Abutment 1 Measurement: Y1, Y2, Y3 along Y axis, X1, X2, X3, X4 along X axis, and Z1,Z2, ..., Z7 along Z axis, total 84 points.*
 - ✓ *Bent 2 Measurement: Y1, Y3, Y5 along Y axis, X1, X2, X3, X4 along X axis, and Z1,Z2, ..., Z7 along Z axis, total 84 points.*
 - ✓ *Measurement points sequence:*

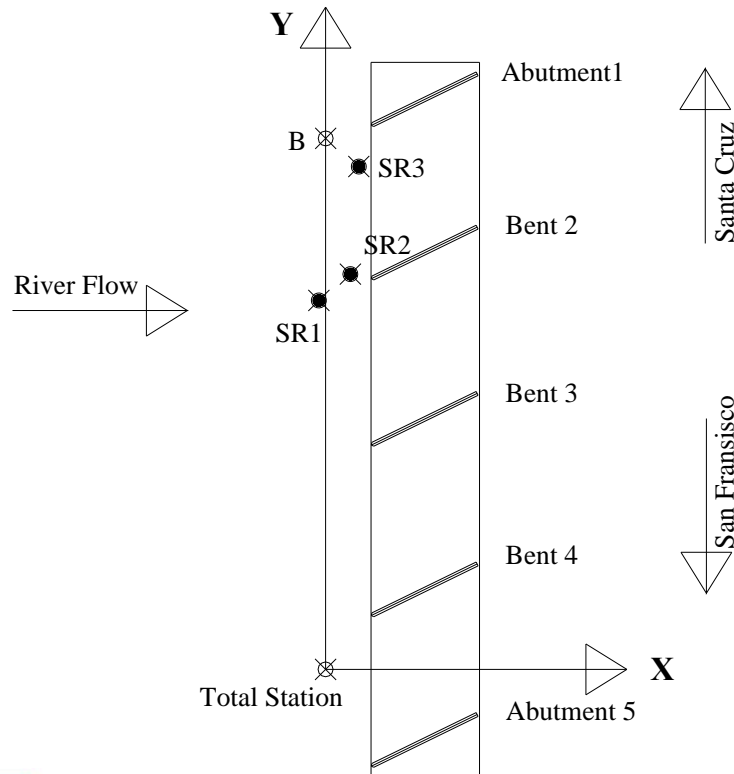


FIELD TEST DEMONSTRATION

- Test Procedure

- Deploy Three Smart Rocks

- ✓ Smart Rock 1 (SR1) & Smart Rock 2 (SR2) around Bent 2
 - ✓ Smart Rock 3 (SR3) around Abutment 1



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FIELD TEST DEMONSTRATION

- Test Procedure
 - Deploy Three Smart Rocks



FIELD TEST DEMONSTRATION

- **Test Procedure**

- **Measure the Total Magnetic Field Intensity**

- ✓ *Magnetic field from both smart rock and AMF.*
 - ✓ *Abutment 1 Measurement: Y1, Y2, Y3 along Y axis, X1, X2, X3, X4 along X axis, and Z1,Z2, ..., Z6 along Z axis, total 72 points.*
 - ✓ *Bent 2 Measurement: Y1, Y3, Y5 along Y axis, X1, X2, X3, X4 along X axis, and Z1,Z2, ..., Z7 along Z axis, total 84 points.*
 - ✓ *Measurement points sequence same as that of AMF.*



FIELD TEST DEMONSTRATION

- **Test Results**

- **Coordinates and Intensities at Measurement Points around Abutment 1**

		Measurement Points Coordinate (m)			N42 Magnet Factor (nT.m ³)	AMF Intensity (nT)				SR3 & AMF Intensity (nT)			
		X _i	Y _i	Z _i	K	B _{XA}	B _{YA}	B _{ZA}	B _A	B _X	B _Y	B _Z	B
Y1X2	Z1	0.656	42.259	-0.942	86521	-18675	-9823	-40007	45230	-17485	-6252	-41897	45828

	Z6	0.768	42.345	0.573	86521	-18661	-9888	-40226	45433	-19943	-7237	-40802	45988
Y1X3	Z1	1.693	42.293	-1.141	86521	-18243	-9707	-39974	45000	-13343	-8111	-48963	51393

	Z6	1.736	42.275	0.366	86521	-18878	-9675	-40509	45727	-19475	-7190	-42452	47256
Y1X4	Z1	2.341	42.387	-1.085	86521	-16406	-10804	-40258	44795	-13358	-11669	-54780	57580

	Z6	2.444	42.329	0.319	86521	-17707	-10784	-41228	46147	-18941	-7994	-44345	48879
Y2X2
Y2X3
Y2X4
Y3X2
Y3X3
Y3X4



FIELD TEST DEMONSTRATION

- Test Results
 - Localization of SR3

Point Name		Measurement Points Coordinate (m)			N42 Magnet Factor (nT.m ³)	AMF Intensity (nT)			SR3 & AMF Intensity (nT)
		X _i	Y _i	Z _i	K	B _{XA}	B _{YA}	B _{ZA}	B
Y1X2	Z1	0.656	42.259	-0.942	86521	-18675	-9823	-40007	45828

	Z6	0.768	42.345	0.573	86521	-18661	-9888	-40226	45988
Y1X3	Z1	1.693	42.293	-1.141	86521	-18243	-9707	-39974	51393

	Z6	1.736	42.275	0.366	86521	-18878	-9675	-40509	47256
Y1X4	Z1	2.341	42.387	-1.085	86521	-16406	-10804	-40258	57580

	Z6	2.444	42.329	0.319	86521	-17707	-10784	-41228	48879
...	
Predicted SR3 Location		2.789	41.302	-2.823	NA				
Measured SR3 Location		2.714	41.104	-2.527					
Location Prediction Error for SR3		0.075	0.198	-0.296					
SRSS Error in Coordinate		0.364							



FIELD TEST DEMONSTRATION

- I-44 Roubidoux Creek Bridge, MO (Bent 7 downstream)

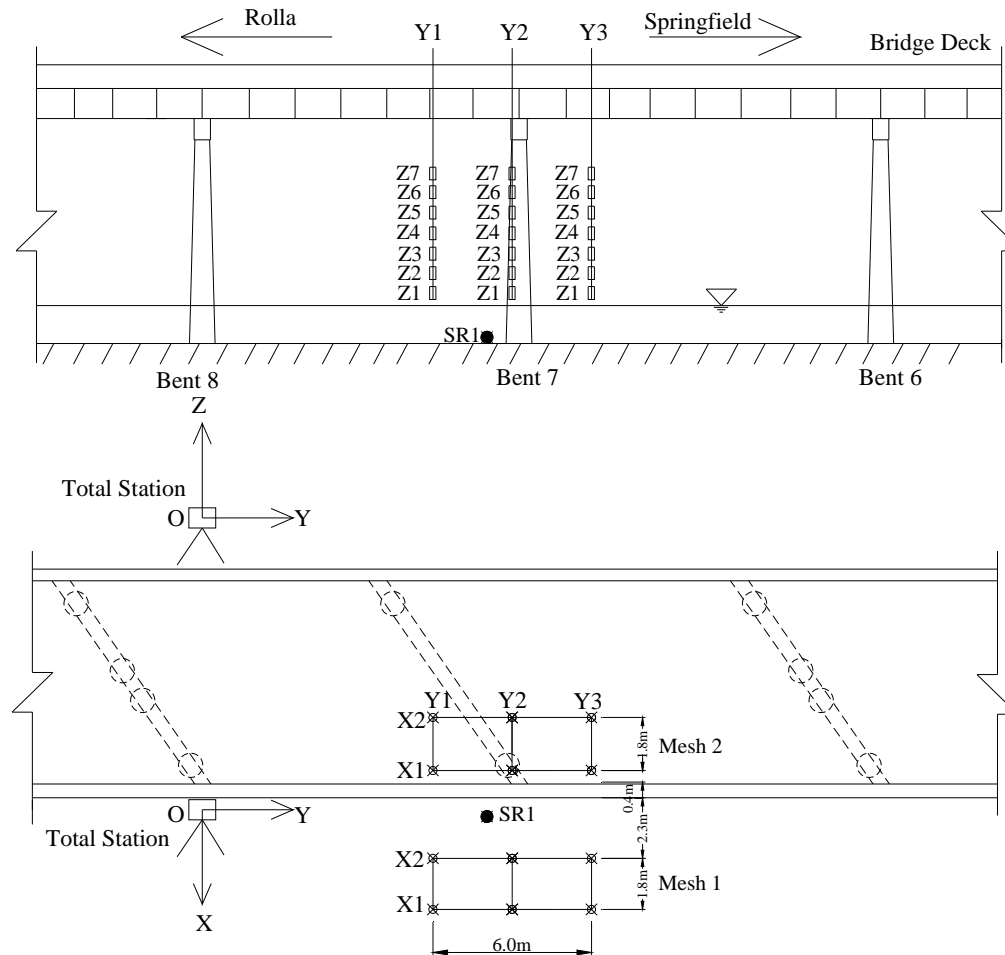


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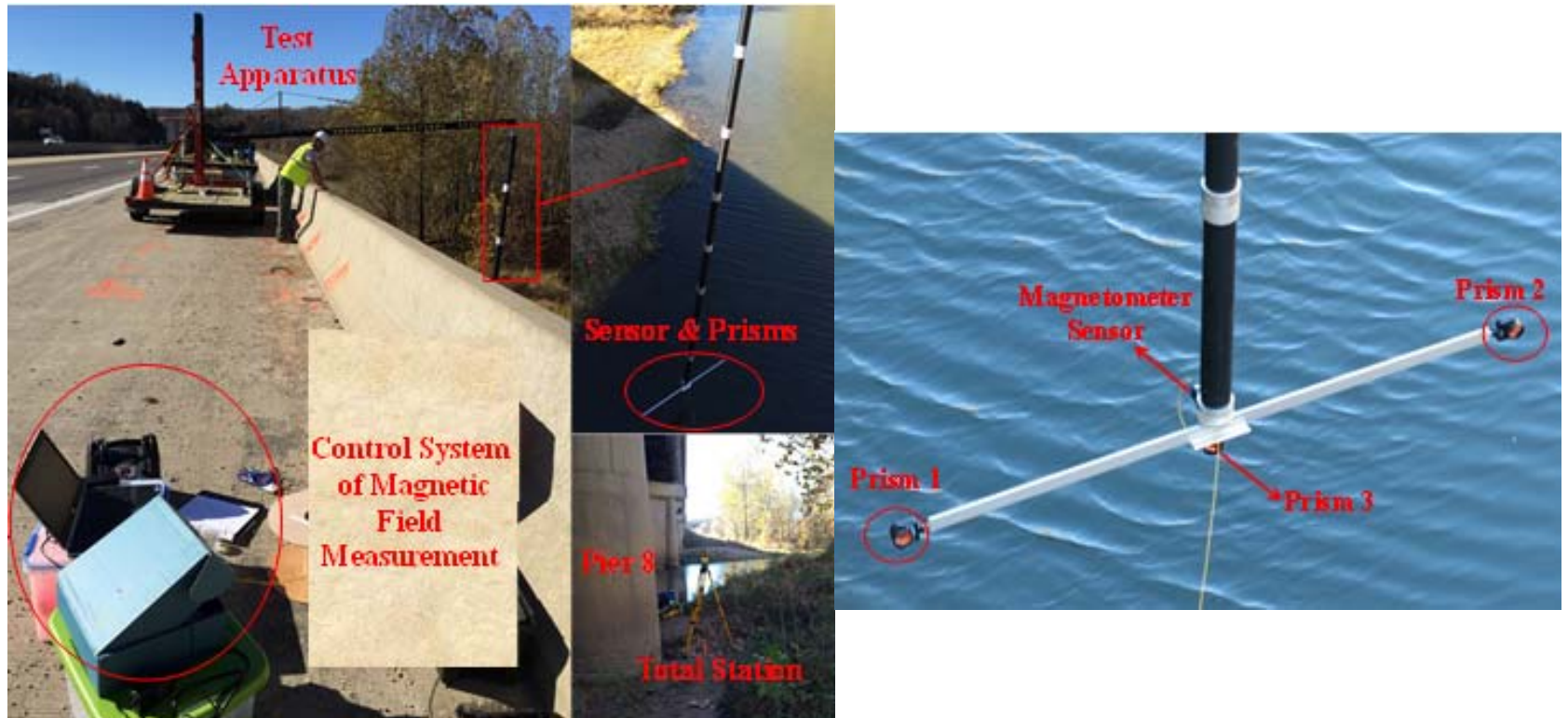
FIELD TEST DEMONSTRATION

- Measurement Station Layout on Bridge Deck



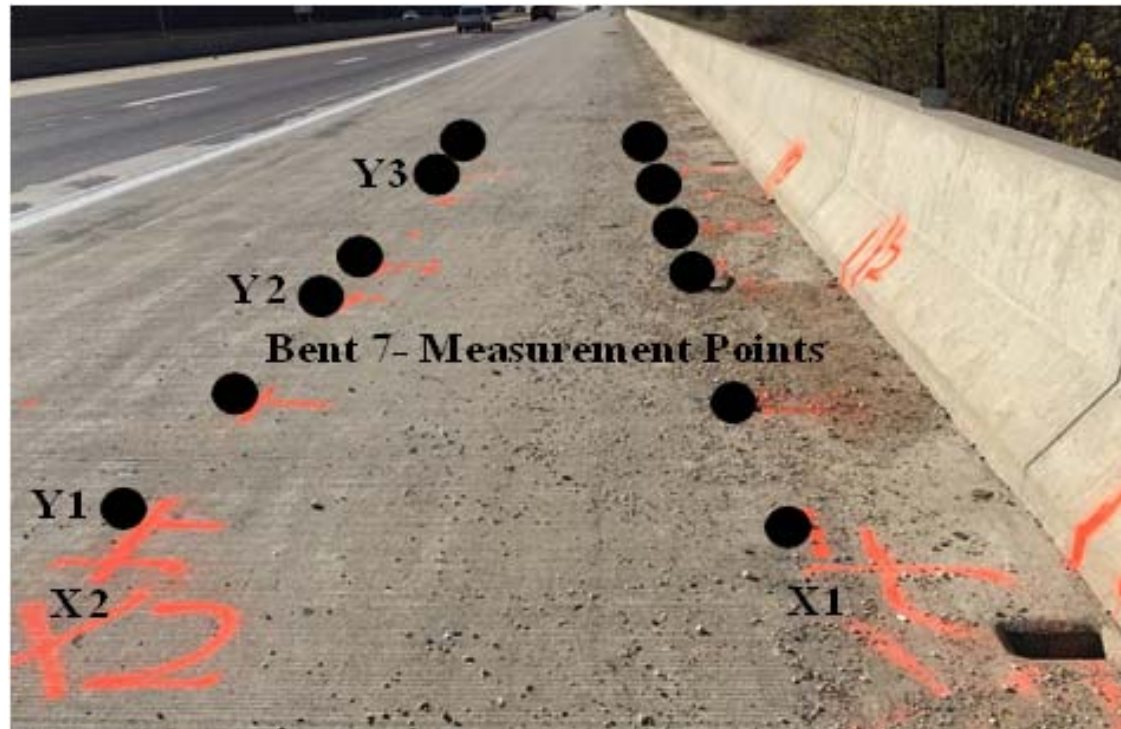
FIELD TEST DEMONSTRATION

- Test Setup and Layout



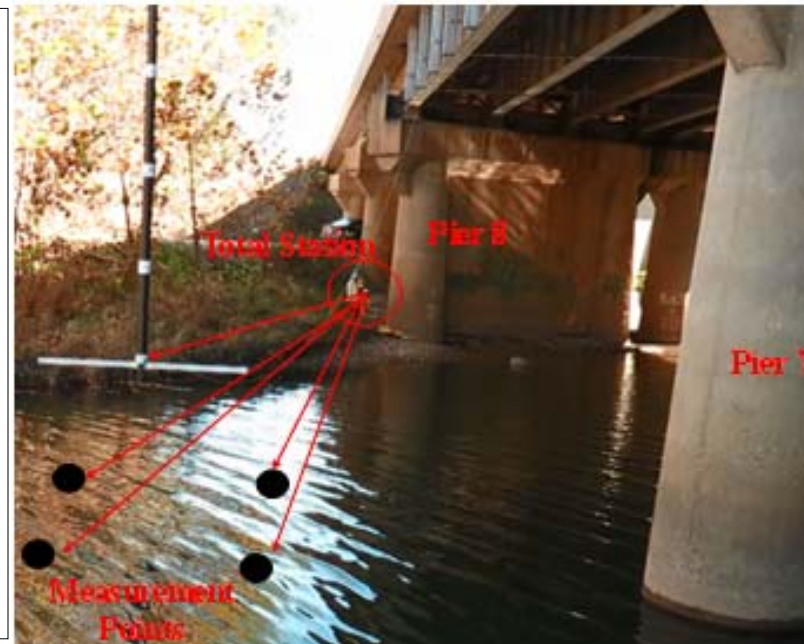
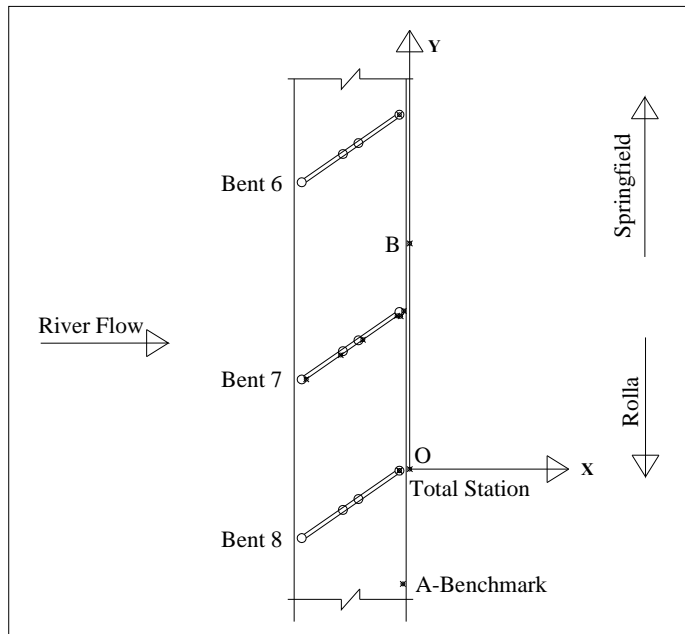
FIELD TEST DEMONSTRATION

- **Test Set up and Layout**
 - **Measurement Points Layout on the Bridge Deck**



FIELD TEST DEMONSTRATION

- Test Procedure
 - Set a Cartesian coordinate system O-XY

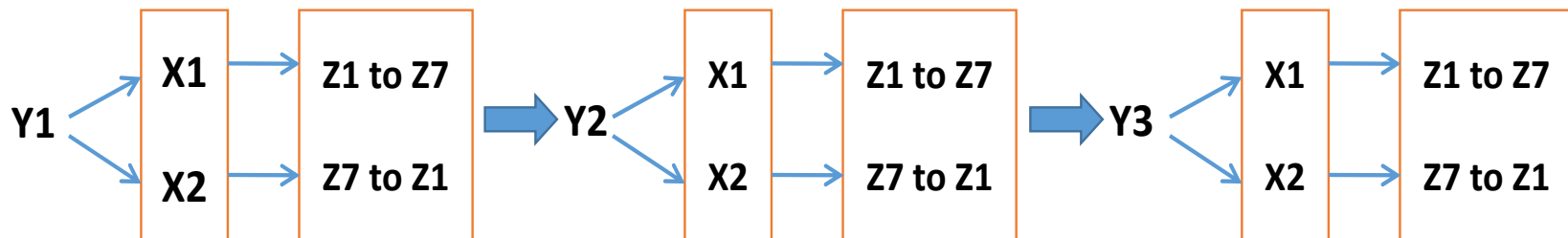


FIELD TEST DEMONSTRATION

- **Test Procedure**

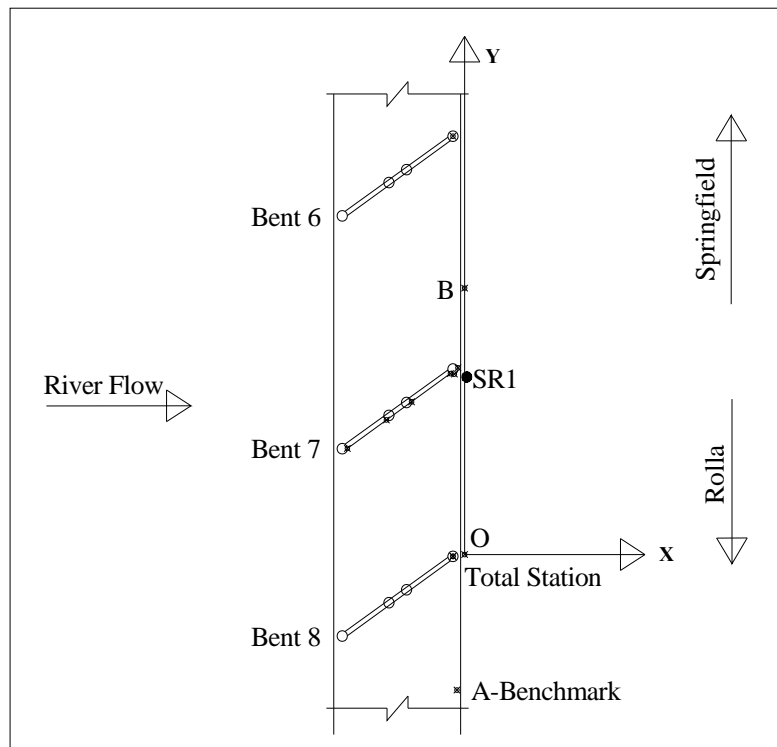
- **Ambient Magnetic Field Measurement**

- ✓ *Magnetic field from Earth and ambient ferromagnetic constructions*
 - ✓ *Conduct before deployment of the smart rock*
 - ✓ *Bent 7 Measurement: Y1, Y2, Y3 along Y axis, X1, X2 along X axis, and Z1, Z2, ..., Z7 along Z axis, total 42 points.*
 - ✓ *Measurement points sequence:*



FIELD TEST DEMONSTRATION

- **Test Procedure**
 - **Deployment of Smart Rocks**
 - ✓ *Smart Rock 1 (SR1) around Bent 7*



FIELD TEST DEMONSTRATION

- **Test Procedure**

- **Measure the Total Magnetic Field Intensity**

- ✓ *Magnetic field from both smart rock and AMF.*
 - ✓ *Bent 7 Measurement: Y1, Y2, Y3 along Y axis, X1, X2, along X axis, and Z1,Z2, ..., Z7 along Z axis, total 42 points.*
 - ✓ *Measurement points sequence same as that of AMF.*



FIELD TEST DEMONSTRATION

- Test Results
 - Coordinates and Intensities at Measurement Points around Bent 7

		Measurement Points Coordinate (m)			N42 Magnet Factor (nT.m ³)	AMF Intensity (nT)				SR3 & AMF Intensity (nT)			
		X _i	Y _i	Z _i	K	B _{XA}	B _{YA}	B _{ZA}	B _A	B _X	B _Y	B _Z	B
Y1X1	Z1	3.854	21.793	-1.002	86521	22781	1016	-48909	53964	21379	-827	-48734	53224

	Z7	3.834	21.554	0.795	86521	22631	2399	-48778	53826	22073	253	-48957	53703
Y1X2	Z1	2.068	21.869	-0.993	86521	22776	1666	-48933	53999	18988	6554	-49341	53274

	Z7	2.083	21.606	0.781	86521	22496	3237	-49477	54447	21054	7653	-50118	54896
Y2X1
Y2X2
Y3X1
Y3X2



FIELD TEST DEMONSTRATION

- **Test Results**
 - Localization of SR1

	X_M/m	Y_M/m	Z_M/m
Predicted SR1 Location	0.063	23.491	-3.032
Measured SR1 Location	0.089	23.235	-3.042
Location Prediction Error for SR1	0.026	0.256	-0.010
SRSS Error in Coordinate	0.258m		



FIELD TEST DEMONSTRATION

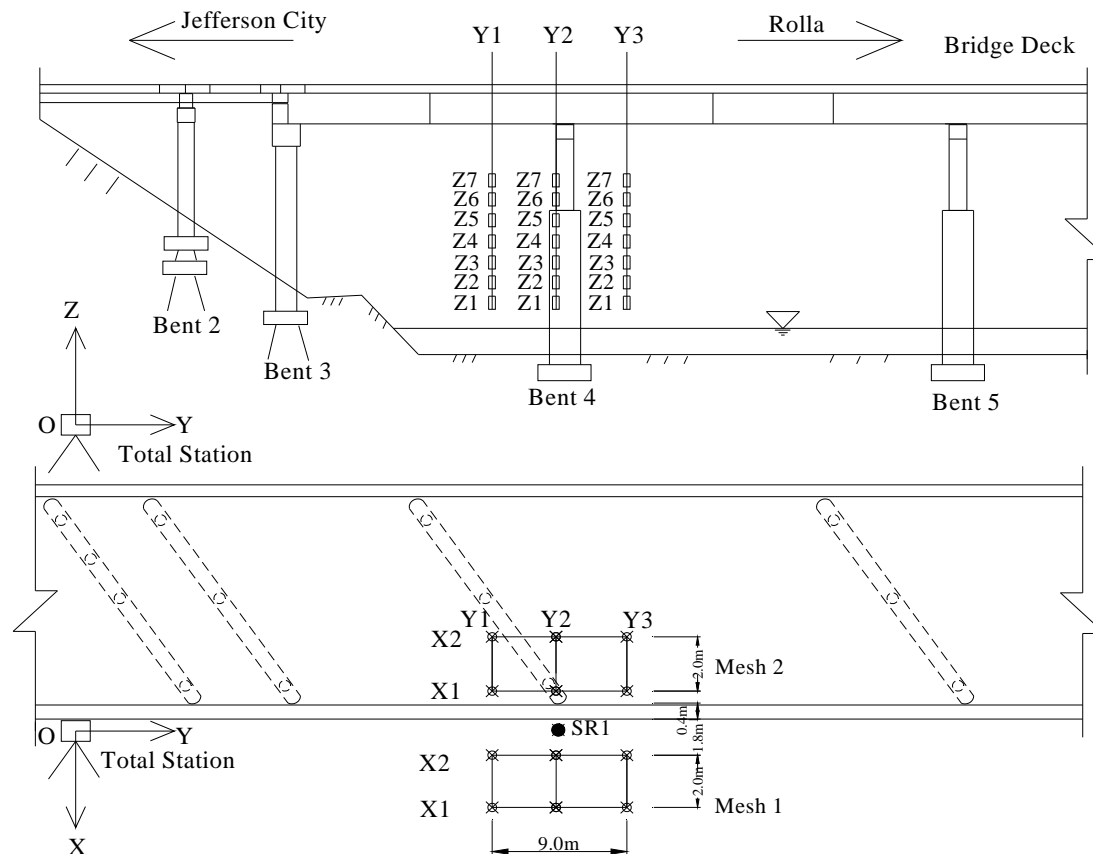
- US63 Gasconade River Bridge, MO (Bent 4 upstream)

US63 Gasconade River Bridge, Br. No A3760



FIELD TEST DEMONSTRATION

- Measurement Station Layout on Bridge Deck



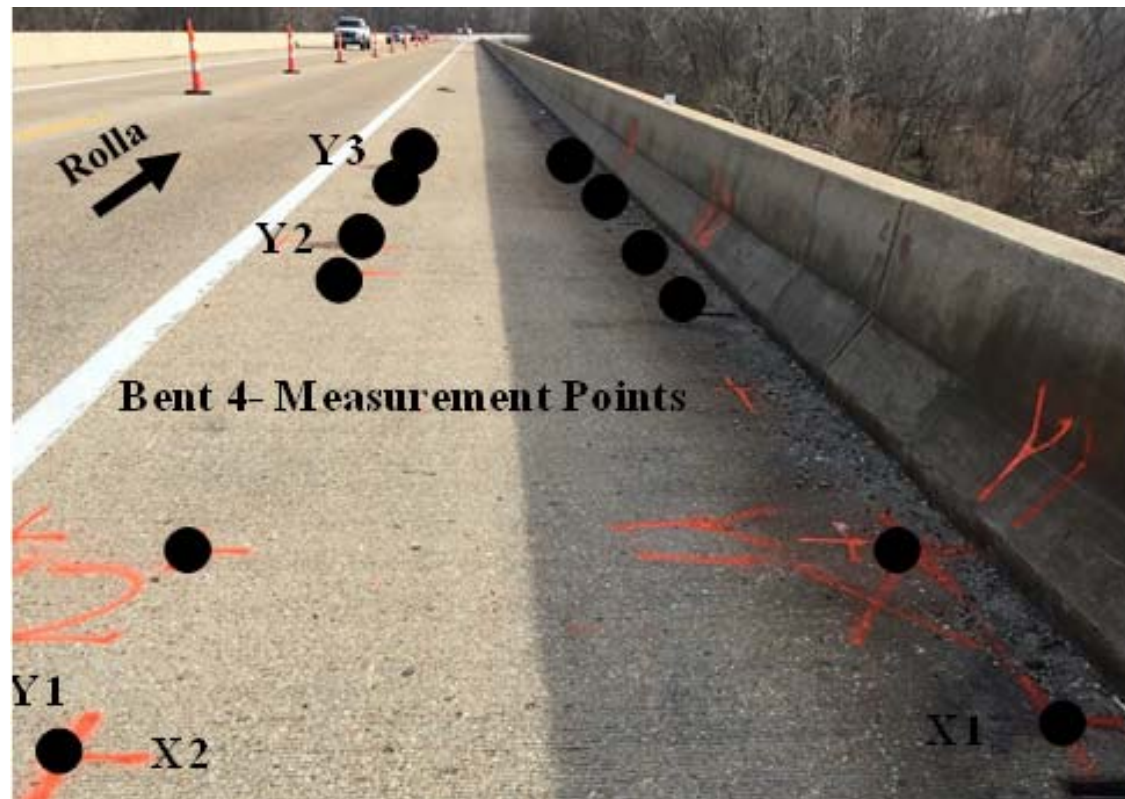
FIELD TEST DEMONSTRATION

- Test Setup and Layout



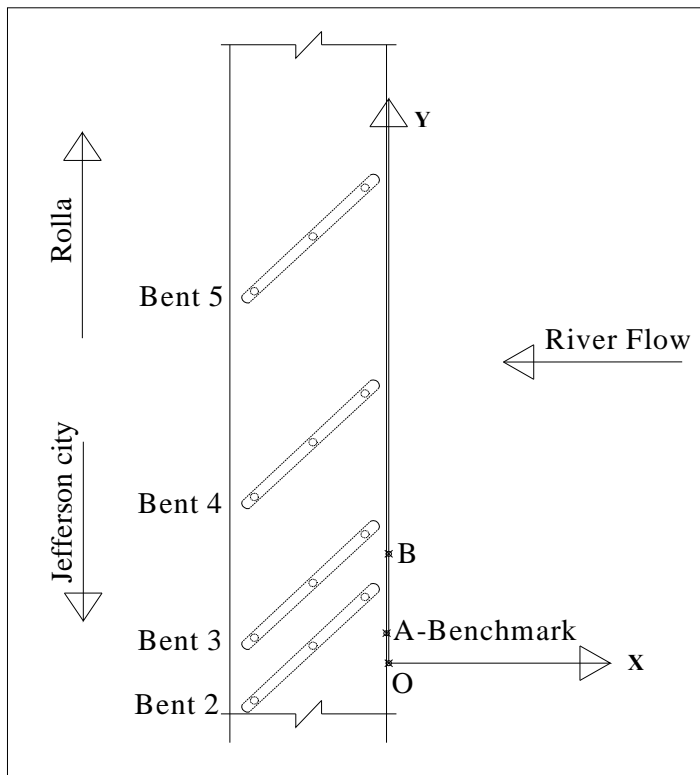
FIELD TEST DEMONSTRATION

- **Test Set up and Layout**
 - **Measurement Points Layout on the Bridge Deck**



FIELD TEST DEMONSTRATION

- Test Procedure
 - Set a Cartesian coordinate system O-XY

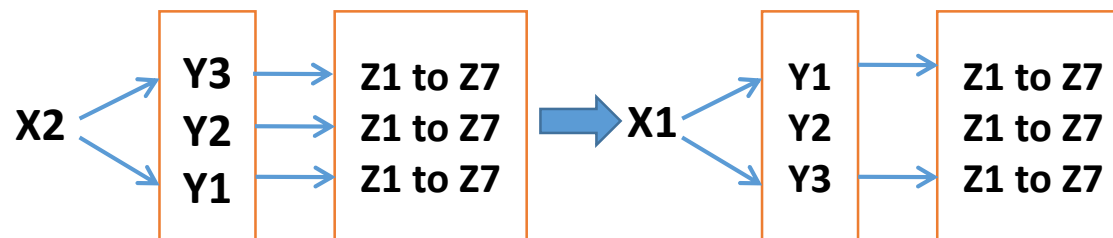


FIELD TEST DEMONSTRATION

- **Test Procedure**

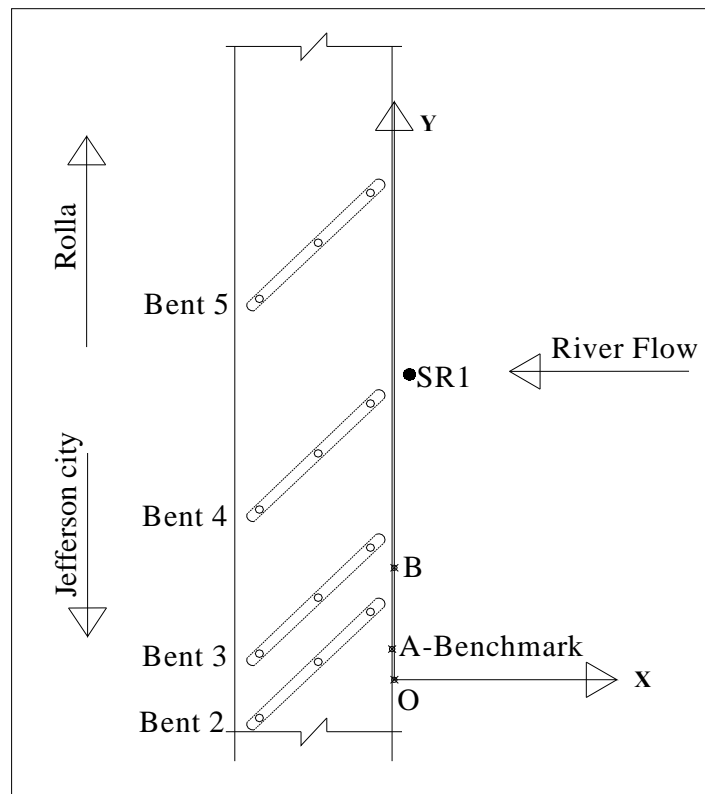
- **Ambient Magnetic Field Measurement**

- ✓ *Magnetic field from Earth and ambient ferromagnetic constructions*
 - ✓ *Conduct before deployment of the smart rock*
 - ✓ *Bent 4 Measurement: Y1, Y2, Y3 along Y axis, X1, X2 along X axis, and Z1,Z2, ..., Z7 along Z axis, total 42 points.*
 - ✓ *Measurement points sequence:*



FIELD TEST DEMONSTRATION

- **Test Procedure**
 - **Deployment of Smart Rocks**
 - ✓ *Smart Rock 1(SR1) around Bent 4*

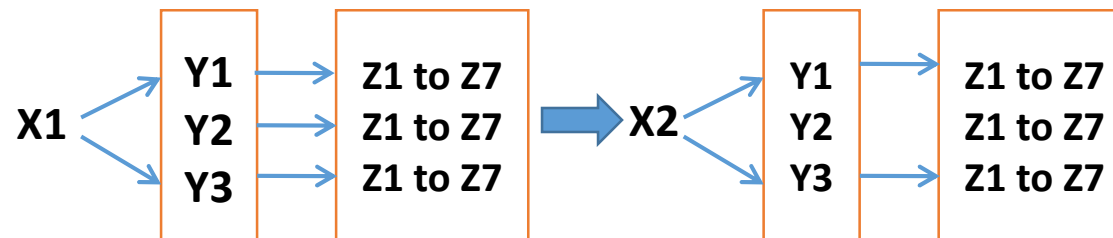


FIELD TEST DEMONSTRATION

- **Test Procedure**

- **Measure the Total Magnetic Field Intensity**

- ✓ *Magnetic field from both smart rock and AMF.*
 - ✓ *Bent 7 Measurement: Y1, Y2, Y3 along Y axis, X1, X2, along X axis, and Z1,Z2, ..., Z7 along Z axis, total 42 points.*
 - ✓ *Measurement points sequence same as that of AMF.*



FIELD TEST DEMONSTRATION

- Test Results
 - Coordinates and Intensities at Measurement Points around Bent 7

		Measurement Points Coordinate (m)			N45 Magnet Factor (nT.m ³)	AMF Intensity (nT)				SR3 & AMF Intensity (nT)			
		X _i	Y _i	Z _i		K	B _{XA}	B _{YA}	B _{ZA}	B _A	B _X	B _Y	B _Z
Y1X1	Z1	2.931	63.700	-11.014	101770	-16429	-6508	-47393	50580	-15752	-5836	-47896	50756

	Z7	3.016	63.526	-9.198	101770	-16125	-5723	-47231	50235	-15817	-5403	-47516	50370
Y1X2	Z1	2.949	68.191	-10.988	101770	-17208	-7072	-46566	50145	-16512	-7637	-46998	50397

	Z7	2.895	67.757	-9.221	101770	-17613	-6984	-46113	49854	-17124	-5446	-46719	50056
Y2X1
Y2X2
Y3X1
Y3X2



FIELD TEST DEMONSTRATION

- **Test Results**

- Localization of SR1
- The ground truth of the coordinate is SR1 was not measured due to the fast water current.
- The predicted location is reasonable according to the relative position to the measurement points.

	X_M/m	Y_M/m	Z_M/m
Predicted SR1 Location	0.460	68.168	-17.002



CONCLUDING REMARKS

- The APUS smart rocks have been deployed at three sites of the Waddell Creek Bridge, CA, the Roubidoux Creek Bridge, MO, and the Gasconade River Bridge, MO.
- The AOS, APSS, and APUS smart rock localization algorithms without and with knowing the magnet polarization in *a priori* have been validated at the three sites, all giving satisfactory results ($\ll 0.5$ m).
- The test crane can be set on a trailer and moved as needed in application.



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